

Extending Linux with Arduinos

Leveraging the Ecosystem

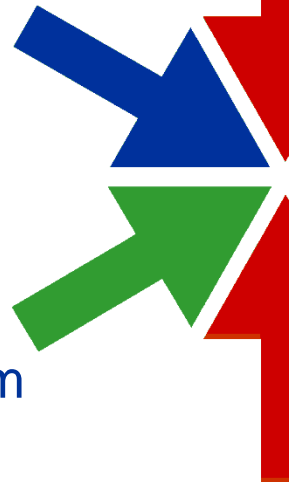
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What We Will Talk About...

- ✚ What is an Arduino?
- ✚ Development model
- ✚ Why Linux comes up short
- ✚ Extending Linux with external μ Cs
- ✚ Connectivity options
- ✚ Summary

What is an Arduino?

- ✖ Arduino is an open-source SBC based on the Atmel AVR microcontroller line
- ✖ The Arduino family uses the Atmel ATmega processor line
 - ▶ Purchased from Nordic Semiconductor
 - **According to Atmel, AVR doesn't stand for anything**
- ✖ Using the AVR is like a trip back to the late 1970s
 - ▶ 8-bit processor with very limited address space
- ✖ Fortunately, the architecture is optimized to execute a HOL like C/C++
 - ▶ 32 8-bit registers
 - ▶ About 1 MIPs/MHz
- ✖ Most processors are either 8MHz or 16MHz
- ✖ The goal of the Arduino project was to enable non-technical users **with a platform that allowed them to interact with the “real world”** in the form of sensors and actuators
 - ▶ Originally conceived as a means to create interesting designs and art



Arduino in the Marketplace

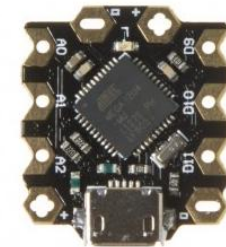
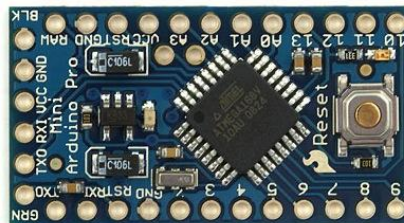
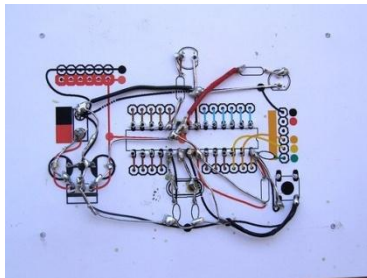
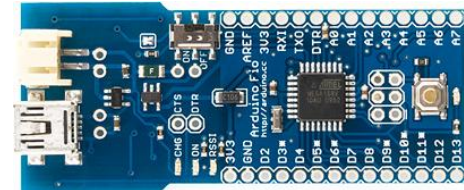
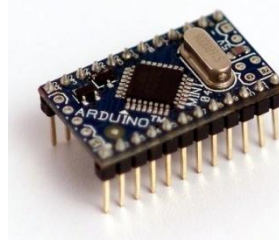
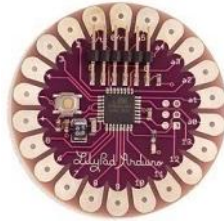
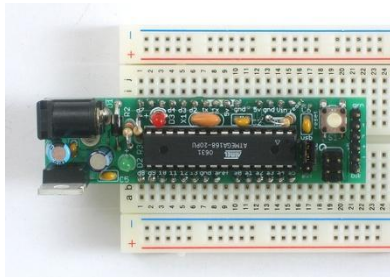
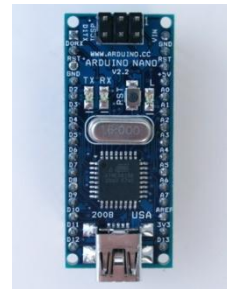
- ✖ Arduino are cheap and ubiquitous
 - ▶ They range from \$8 to as much as \$120 depending on options installed
- ✖ Arduino are available from multiple sources including:
 - ▶ RadioShack, Frys, MicroCenter, SparkFun and many others
- ✖ Applications ranging from simple LED art to fully autonomous multi-rotor sensing and camera platforms with GPS
- ✖ There is estimated to be over 1,000,000 Arduino and clones in use today



The Arduino Project

- ✖ Ivrea, Italy is the home town of Olivetti
 - ▶ Essentially, the Italian version of IBM
- ✖ Started in 2005 at the Interaction Design Institute Ivrea in Ivrea, **Italy, the Arduino Project's stated mission is:**
 - ▶ Arduino is an open-source electronics prototyping platform based on flexible, easy-to-use hardware and software. It's intended for artists, designers, hobbyists, and anyone interested in creating interactive objects or environments.
- ✖ **The project is forked from the “Wiring” project created by Hernando Barragan as part of his thesis work at Ivrea**
- ✖ **Only “official” boards can carry the Arduino name**
 - ▶ Uno, Diecimila, Duemilanove, Mega2560, etc.
- ✖ However, there are a number of commercially available clones
 - ▶ Freeduino, Seeeduino, Boarduino, Netduino, etc.
- ✖ Most Arduinos use the megaAVR series of chips
 - ▶ ATmega8, ATmega168, ATmega328, ATmega1280 or ATmega2560
 - These have varying amounts of RAM, Flash and I/O
 - ▶ Arduino Due uses ARM Cortex M3 (Atmel SAM3x)

Example Arduinos/Clones



Memory by Processor Type

✖ This chart shows how much storage you have:

	ATMega168	ATMega328P	ATmega1280	ATmega2560
Flash (1 Kbyte used for bootloader)	16 KBytes	32 KBytes	128 KBytes	256 KBytes
SRAM	1024 bytes	2048 bytes	8 KBytes	8 KBytes
EEPROM	512 bytes	1024 bytes	4 KBytes	4 KBytes

✖ There are special commands for reading/writing the EEPROM to use as persistent storage of static data such as display strings

Overview of I/O Capabilities

- ✖ The major variants:
 - ▶ ATmega328 (Uno)
 - 14 DIO (4 with PWM)
 - 6 analog inputs
 - 2 external interrupt lines
 - 1 UART (simple 3 wire)
 - 2 8-bit, 1 16-bit timer
 - JTAG
 - ▶ ATmega2560 (Mega2560/ADK)
 - 54 DIO (14 with PWM)
 - 16 analog inputs
 - 6 external interrupt lines
 - 4 UARTS (simple 3 wire)
 - 2 8-bit, 4 16-bit timers
 - JTAG



- ✖ Most Arduinos implement a USB to Serial interface for the UART
 - ▶ Used to program the Flash as well as for serial I/O
- ✖ Support for I2C, SPI, TWI, UART, A/D, D/A, PWM and GPIOs are all built into the easy-to-use libraries
- ✖ There is support for Ethernet via the Wiznet 10/100 Mbps W5100 interface (SPI)
- ✖ Wi-Fi, Zigbee and Bluetooth are supported too as is the 423 MHz ISM band
 - ▶ RF ranges can be > 2 miles in the lower RF bands

Why Hasn't Linux Killed Arduino?

✖ With the Beaglebone Black, Raspberry Pi, Udoo and others being so cheap, why does Arduino continue to exist?

▶ **It's not cost**

- Arduinos can cost more than the BBB or RPi

✖ Size and power are part of it

- ▶ You can buy really tiny Arduino clones
- ▶ You can run an Arduino for months from AA batteries



✖ Complexity is a big factor

- ▶ Just the process of getting Linux to run on BBB or RPi can be daunting to non-Linux folks

✖ **However, it's the Arduino community and ecosystem that dwarfs what we've accomplished so far with the Linux platforms**

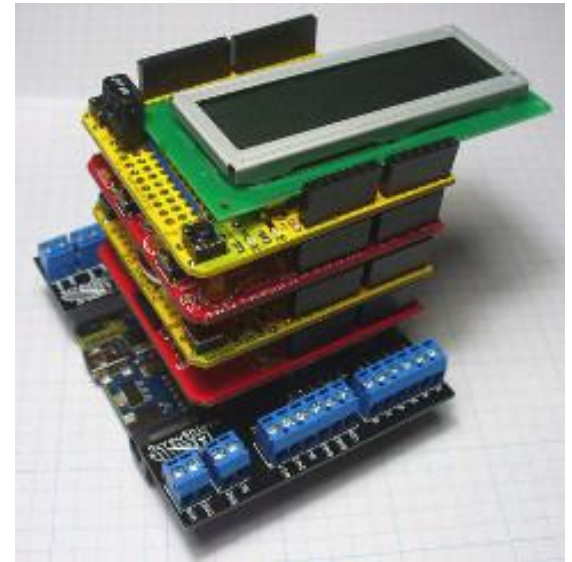
- ▶ Arduino programming model is dirt-dumb simple
- ▶ Large selection of libraries available in source code
- ▶ I/O expansion selection is mind boggling
 - The Arduino shield pin-out is almost universal

I/O Shields

✦ A variety of shields are available:

- ▶ Bluetooth, ZigBee, Ethernet, GPS, protoboard, relays, MIDI, SD Card, LCD, motor controllers, joysticks and many, many more
- ▶ Over 250 shields at last count!

✦ Some shields can be stacked to create complex systems



The Arduino Boot Cycle

- ✖ Ranging from .5 to 1KB, the Arduino bootloader is stored in the Flash
 - ▶ Executed on power-on
 - ▶ All Arduino boards already have this installed but you can load your own from the IDE
- ✖ Runs whatever program is stored in Flash
 - ▶ Flash is programmed via JTAG (USB or serial)
- ✖ The programming model is very simple
 - ▶ No RTOS, just a simple run-time executive and C run time
- ✖ No multi-tasking although ISRs are supported
 - ▶ Software interrupts can be simulated using the pin change feature

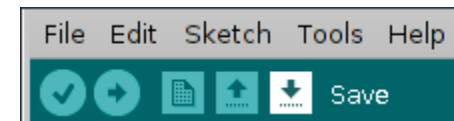
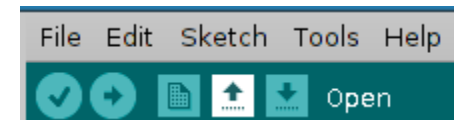
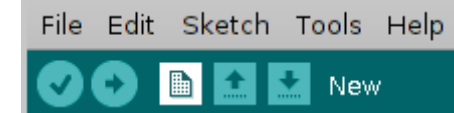
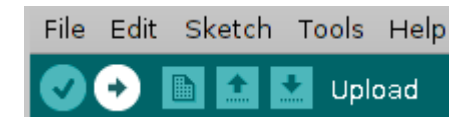
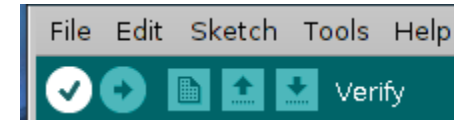
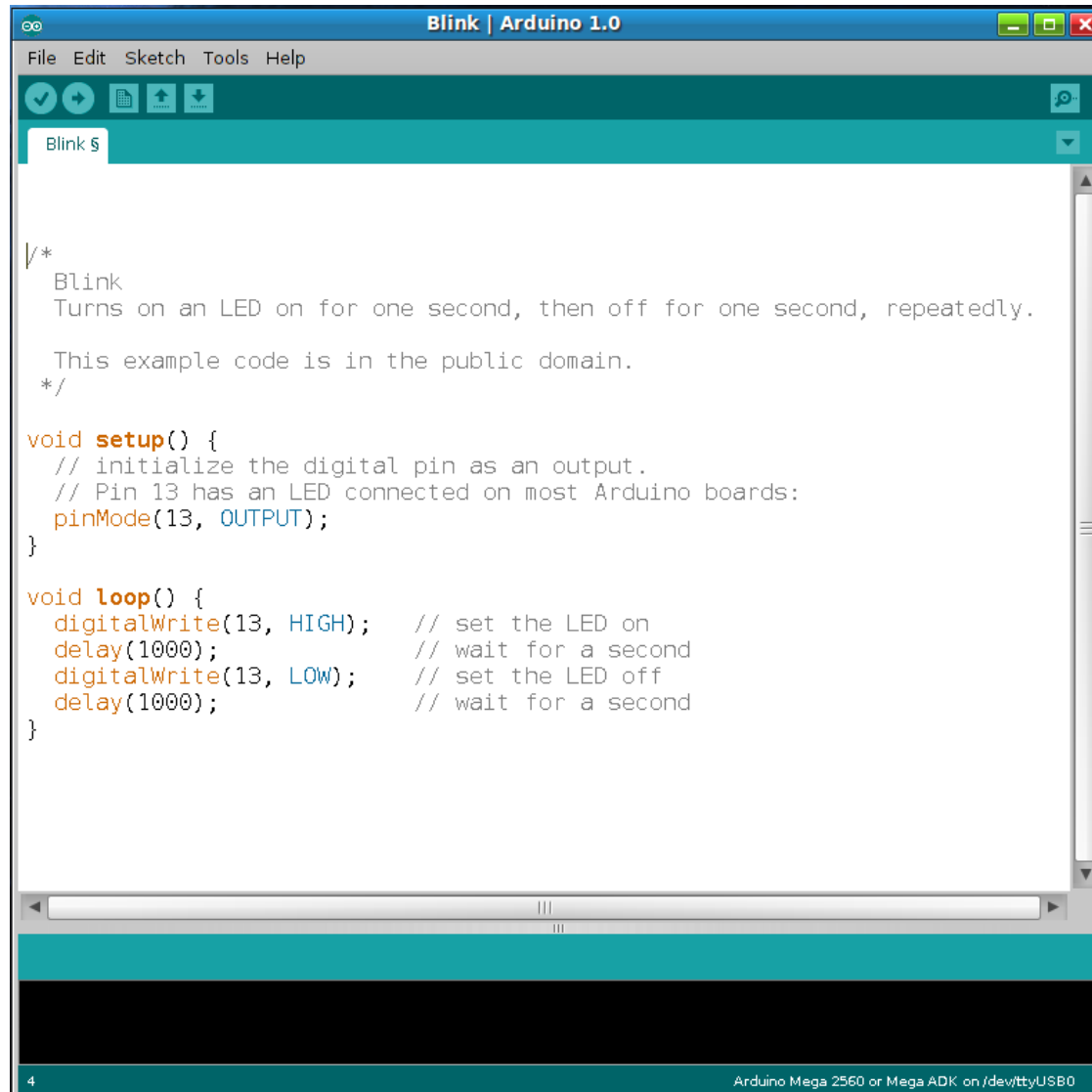
The Arduino Development Environment

- ✖ Just as the hardware is based on the open-source **“wiring” model, the programming model is based on** the open-source Processing Programming Language
 - ▶ Again, targeted at non-professional developers
- ✖ A Java-based IDE is available for Windows, OS/X and Linux
 - ▶ Open-source and free to download
 - <http://arduino.cc/en/Main/Software>
 - ▶ Implements the basics of syntax highlighting, brace matching and automatic indentation
- ✖ The compiler that is included with the IDE is the GNU avr-gcc compiler
- ✖ You can also program in AVR assembler
 - ▶ But, that kind of defeats the easily accessible part of the Arduino

Language Support

- ✖ The Processing language is a restricted subset of C/C++
 - ▶ Heavily leverages the use of libraries to accomplish most operations
- ✖ Most of C/C++ is supported
 - ▶ This includes classes/constructors/destructors, etc.
 - Remember, everything must fit into storage!
- ✖ No PVFs, multiple inheritance, RTTI, etc.
 - ▶ The stuff that eats memory ;-)
- ✖ **int** is 16-bit but **long** is 32-bit
- ✖ **float** and **double** are both 4 bytes
 - ▶ Floating point is done in software so consider converting to fixed point to speed computation
- ✖ Yes, pointers and dereferences are supported!

Example Arduino IDE



Example Sketch

```
/*  
  Blink  
  Turns on an LED on for one second, then off for one second, repeatedly.  
  
  This example code is in the public domain.  
  */  
  
void setup() {  
  // initialize the digital pin as an output.  
  // Pin 13 has an LED connected on most Arduino boards:  
  pinMode(13, OUTPUT);  
}  
  
void loop() {  
  digitalWrite(13, HIGH);    // set the LED on  
  delay(1000);               // wait for a second  
  digitalWrite(13, LOW);     // set the LED off  
  delay(1000);               // wait for a second  
}
```

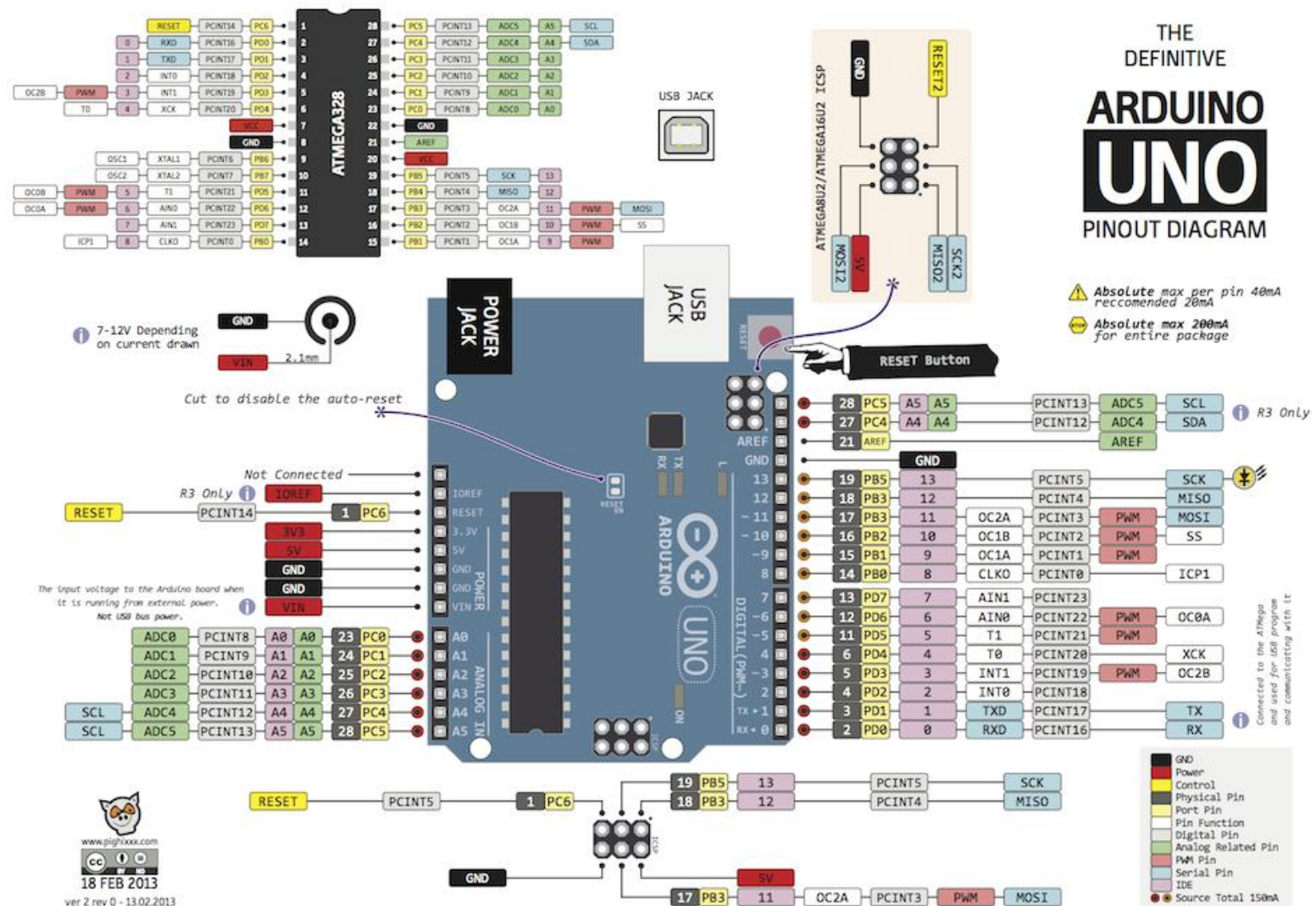
- The **Beaglebone's** BoneScript tries to approximate this API
- **Intel's Galileo board** has a version of the Arduino API ported to it
 - But, still runs Linux natively

A simple ISR

 Here is an example that generates an interrupt every time a rising edge is encountered

```
void setup(void) {  
    attachInterrupt(0, count, RISING); // Captures external  
                                       // interrupt 0  
    Serial.begin(9600);                // Begin Serial at 9600 bps  
    Serial.println(" Initializing, Please wait...");  
  
}  
  
void count() {                        // Function called by AttachInterrupt  
                                     // at interrupt at int 0  
    siPulseCounter++;                // increment the pulse count  
  
}
```

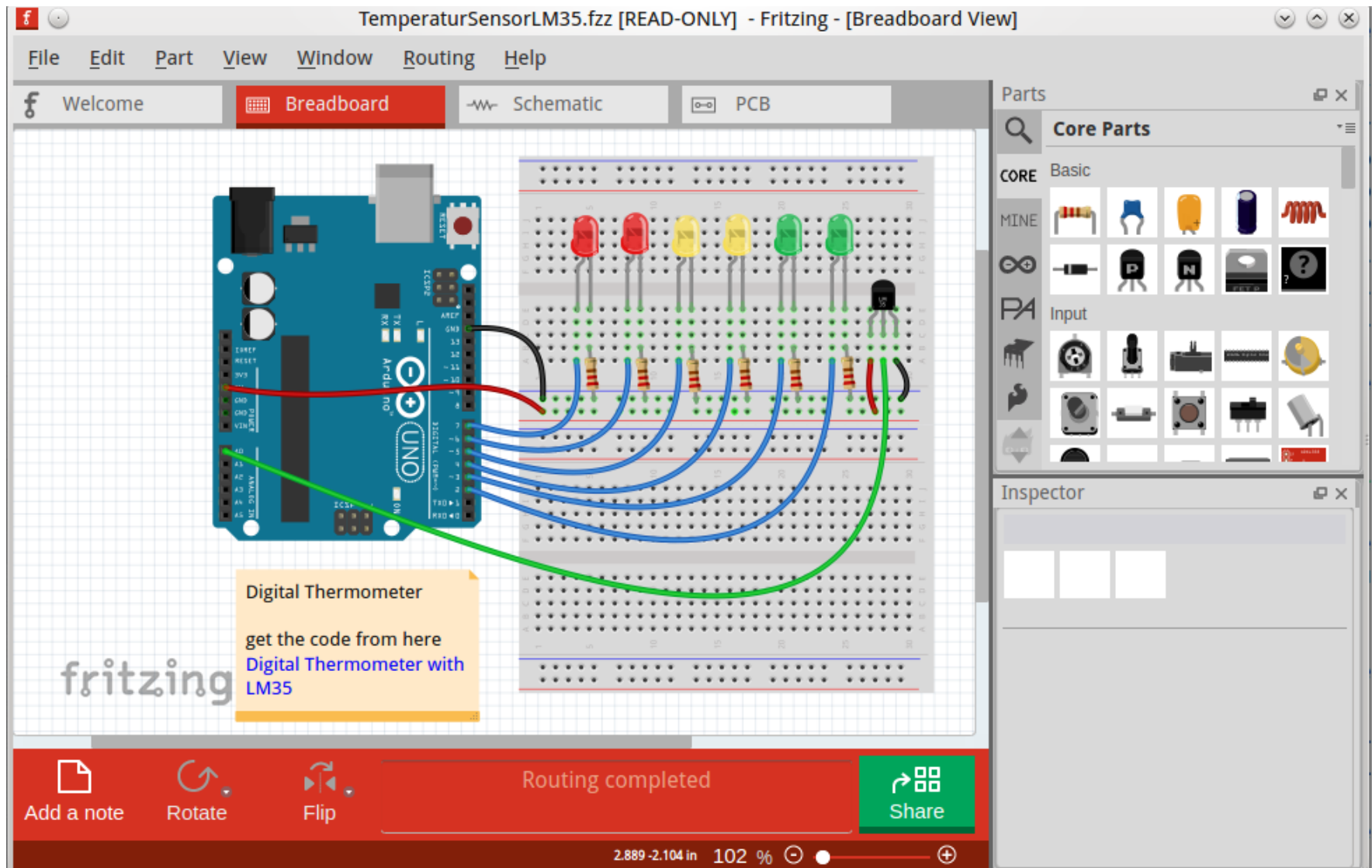
The Arduino Pin-Out



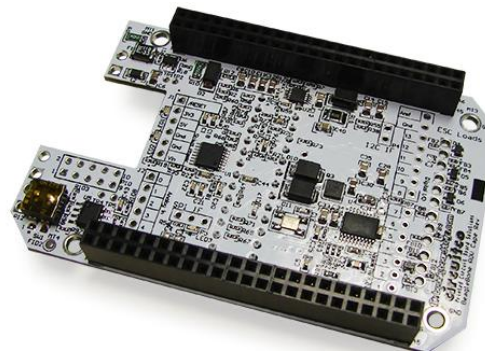
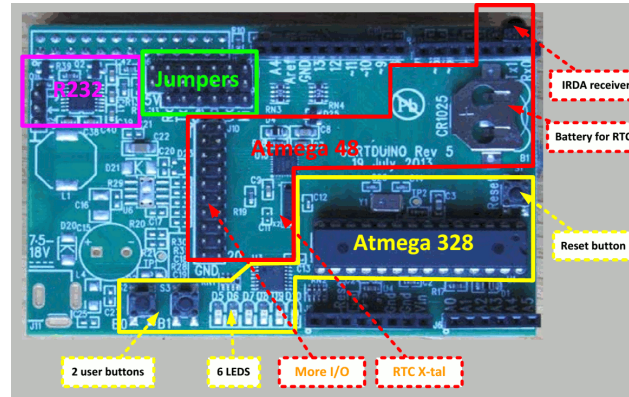
Fritzing Diagrams

- ✖ In order to help non-engineers with wiring prototypes, the Fritzing Diagram approach was created
 - ▶ Developed at the University of Applied Sciences of Potsdam
- ✖ The software is created in the spirit of Processing and Arduino and allows a designer, artist, researcher, or hobbyist to document their Arduino-based prototype and create a PCB layout for manufacturing
 - ▶ Includes the ability to create a schematic as well as the picture of the circuit

Example Fritzing Diagram



Linux/Arduino Boards



Why Extend Linux with Arduinos?

- ✖ With PREEMPT_RT, Linux has excellent timing characteristics
 - ▶ But, this requires patching the kernel and rebuilding
 - Beyond the grasp of even typical power users
- ✖ **PREEMPT_VOLUNTARY can't meet the timing requirements of many real-world applications**
 - ▶ E.g., PWM-based motor controllers
 - ▶ This is the default for most Linux distros
- ✖ x86 may be fast, but one SMI will kill your R-T performance
- ✖ Offloading hard real-time constraints to external processors is often the path of least resistance
 - ▶ **Arduinos are a good option because they're cheap and easy to use**
 - ▶ Prototyping real-world I/O using Arduinos is very straightforward
 - Hundreds of examples available on the web

Example: I2C in Linux vs. Arduino

```
/*+ Opening the bus ++++++
#include <errno.h>
#include <string.h>
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <linux/i2c-dev.h>
#include <sys/ioctl.h>
#include <sys/types.h>
#include <sys/stat.h>
#include <fcntl.h>
int file;
char *filename = "/dev/i2c-1";
if ((file = open(filename, O_RDWR)) < 0) {
    /* ERROR HANDLING: you can check errno to see what went wrong */
    perror("Failed to open the i2c bus");
    exit(1);
}

/*+ Initiating Comms ++++++
int addr = 0x48; // The I2C address of the device
if (ioctl(file, I2C_SLAVE, addr) < 0) {
    printf("Failed to acquire bus access and/or talk to slave.\n");
    /* ERROR HANDLING; you can check errno to see what went wrong */
    exit(1);
}

/*+ Reading from device ++++++
unsigned char buf[10] = {0};

for (int i = 0; i<4; i++) {
    // Using I2C Read
    if (read(file,buf,2) != 2) {
        /* ERROR HANDLING: i2c transaction failed */
        printf("Failed to read from the i2c bus: %s.\n", strerror(errno));
        printf("\n\n");
    } else {
        /* Device specific stuff here */
    }
}
```

```
1 // This example code is in the public domain.
2
3 #include <Wire.h>
4
5 void setup()
6 {
7     Wire.begin(4); // join i2c bus with address #4
8     Wire.onReceive(receiveEvent); // register event
9     Serial.begin(9600); // start serial for output
10 }
11
12 void loop()
13 {
14     delay(100);
15 }
16
17 // function that executes whenever data is received from master
18 // this function is registered as an event, see setup()
19 void receiveEvent(int howMany)
20 {
21     while(1 < Wire.available()) // loop through all but the last
22     {
23         char c = Wire.read(); // receive byte as a character
24         Serial.print(c); // print the character
25     }
26     int x = Wire.read(); // receive byte as an integer
27     Serial.println(x); // print the integer
28 }
```

Connectivity Options

- ✖ Since Arduinos support virtually every type of connectivity found in the typical Linux **system, it's easy to add them to the mix**
 - ▶ Wi-Fi, Ethernet, Bluetooth, I2C, SPI, UART, etc.
- ✖ My robot from the showcase uses a BBB talking to an Atmel 328 via I2C
- ✖ Use the Arduino board for the electrical interface and as a smart buffer
 - ▶ **Jitter on the Linux side won't impact the control system performance**

Summary

- ✖ Arduinos are great for quick prototypes
 - ▶ Development environment is easy to use
 - Lots of examples on the web
 - ▶ Bare-metal approach gives you great repeatability
- ✖ Linux can require considerable tweaking to get to the point that you can meet R-T deadlines reliably
- ✖ Combining the two environments give you the best of both worlds
 - ▶ More and more combination boards are coming out to keep the parts count and costs down